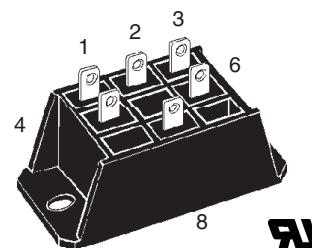
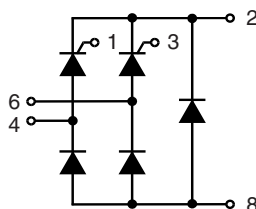


Half Controlled Single Phase Rectifier Bridge with Freewheeling Diode

$$I_{dAVM} = 40 \text{ A}$$

$$V_{RRM} = 1400 \text{ V}$$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
1500	1400	VHF 36-14io5



Symbol	Test Conditions	Maximum Ratings
I_{dAV} I_{dAVM} I_{FRMS}, I_{TRMS}	$T_K = 85^\circ\text{C}$, module module per leg	36 A 40 A 28 A
I_{FSM}, I_{TSM}	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0 \text{ V}$ $t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	320 A 350 A
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$ $t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	280 A 310 A
I^2t	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0 \text{ V}$ $t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	500 A ² s 520 A ² s
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$ $t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	390 A ² s 400 A ² s
$(di/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$ $f = 50 \text{ Hz}$, $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$, $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 50 \text{ A}$ 150 A/ μs non repetitive, $I_T = 1/2 I_{dAV}$ 500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$; $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	1000 V/ μs
V_{RGM}		10 V
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$ $t_p = 30 \mu\text{s}$ $t_p = 500 \mu\text{s}$ $t_p = 10 \text{ ms}$	$\leq 10 \text{ W}$ $\leq 5 \text{ W}$ $\leq 1 \text{ W}$
P_{GAVM}		0.5 W
T_{VJ}		-40...+125 °C
T_{VJM}		125 °C
T_{stg}		-40...+125 °C
V_{ISOL}	50/60 Hz, RMS $I_{ISOL} \leq 1 \text{ mA}$ $t = 1 \text{ min}$ $t = 1 \text{ s}$	3000 V~ 3600 V~
M_d	Mounting torque (M5) (10-32 UNF)	2-2.5 Nm 18-22 lb.in.
Weight		50 g

Features

- Package with DCB ceramic base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- 1/4" fast-on terminals
- UL registered E 72873

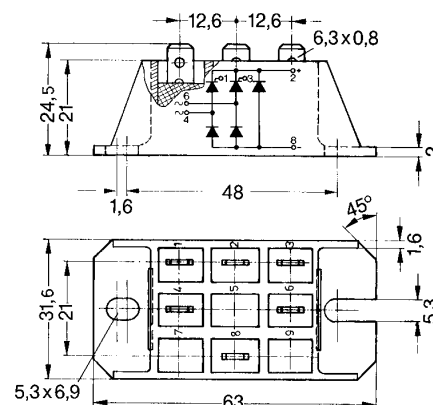
Applications

- Supply for DC power equipment
- DC motor control

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated.
① for resistive load.

IXYS reserves the right to change limits, test conditions and dimensions.

Symbol	Test Conditions	Characteristic Values			
I_R, I_D	$V_R = V_{RRM}; V_D = V_{DRM}$ $T_{VJ} = T_{VJM}$ $T_{VJ} = 25^{\circ}\text{C}$	$\leq$ $\leq$	5 0.3	mA mA	
V_T, V_F	$I_T, I_F = 45\text{ A}; T_{VJ} = 25^{\circ}\text{C}$	$\leq$	1.45	V	
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^{\circ}\text{C}$)		0.85	V	
r_T			13	m Ω	
V_{GT}	$V_D = 6\text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = -40^{\circ}\text{C}$	$\leq$ $\leq$	1.0 1.2	V V	
I_{GT}	$V_D = 6\text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = -40^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	$\leq$ $\leq$ $\leq$ $\leq$	65 80 50	mA mA mA	
V_{GD}	$T_{VJ} = T_{VJM};$ $T_{VJ} = T_{VJM};$	$V_D = 2/3 V_{DRM}$ $V_D = 2/3 V_{DRM}$	$\leq$ $\leq$	0.2 5	V mA
I_L	$I_G = 0.3\text{ A}; t_G = 30\text{ }\mu\text{s};$ $di_G/dt = 0.3\text{ A}/\mu\text{s};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = -40^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	$\leq$ $\leq$ $\leq$	150 200 100	mA mA mA	
I_H	$T_{VJ} = 25^{\circ}\text{C}; V_D = 6\text{ V}; R_{GK} = \infty$	$\leq$	100	mA	
t_{gd}	$T_{VJ} = 25^{\circ}\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3\text{ A}; di_G/dt = 0.3\text{ A}/\mu\text{s}$	$\leq$	2	μs	
t_q	$T_{VJ} = 125^{\circ}\text{C}; I_T = 15\text{ A}; t_p = 300\text{ }\mu\text{s}; V_R = 100\text{ V}$ $di/dt = -10\text{ A}/\mu\text{s}; dv/dt = 20\text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$	typ.	150 75	μs μC	
R_{thJC}	per thyristor (diode); DC current per module		1.15 0.29	K/W K/W	
R_{thJK}	per thyristor (diode); DC current per module		1.55 0.39	K/W K/W	
d_s	Creeping distance on surface		12.6	mm	
d_A	Creepage distance in air		6.3	mm	
a	Max. allowable acceleration		50	m/s ²	

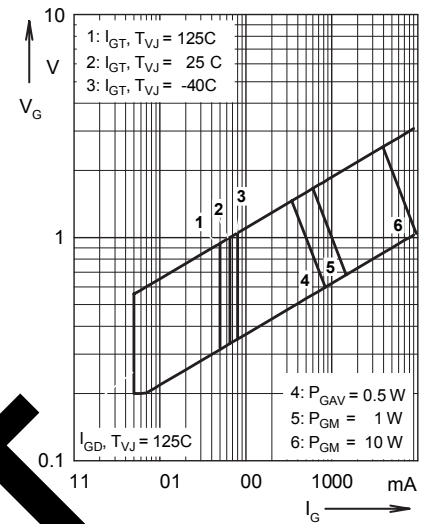


Fig. 1 Gate trigger range

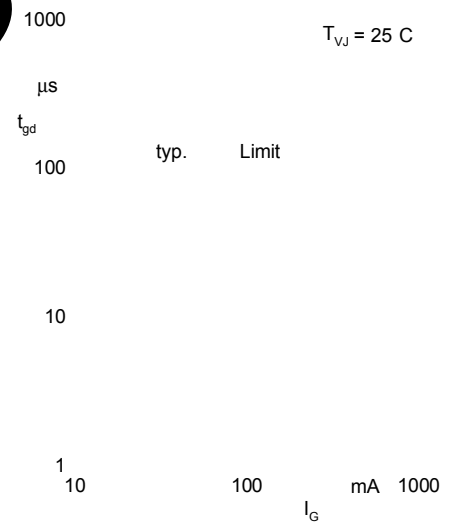


Fig. 2 Gate controlled delay time t_{gd}

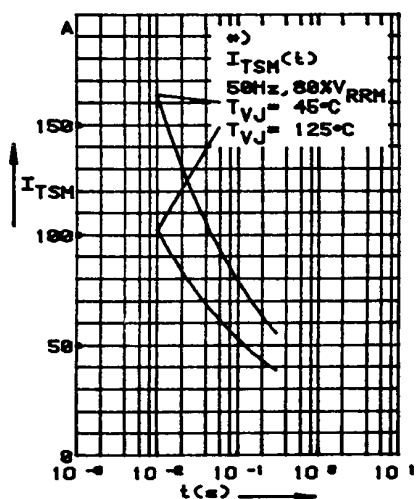


Fig. 3 Surge overload current per chip
 I_{FSM} : Crest value, t : duration

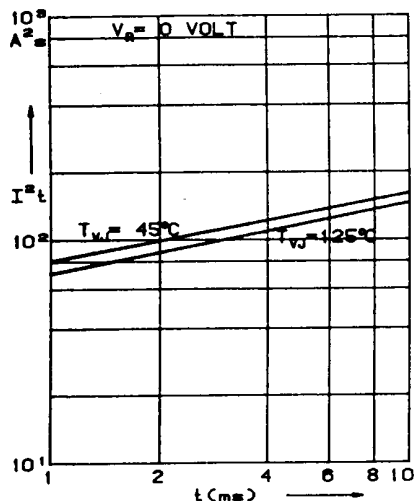


Fig. 4 I^2t versus time (1-10 ms)
per chip

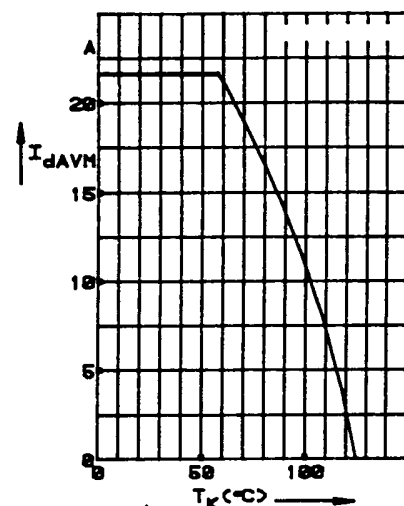


Fig. 5 Max. forward current at
heatsink temperature

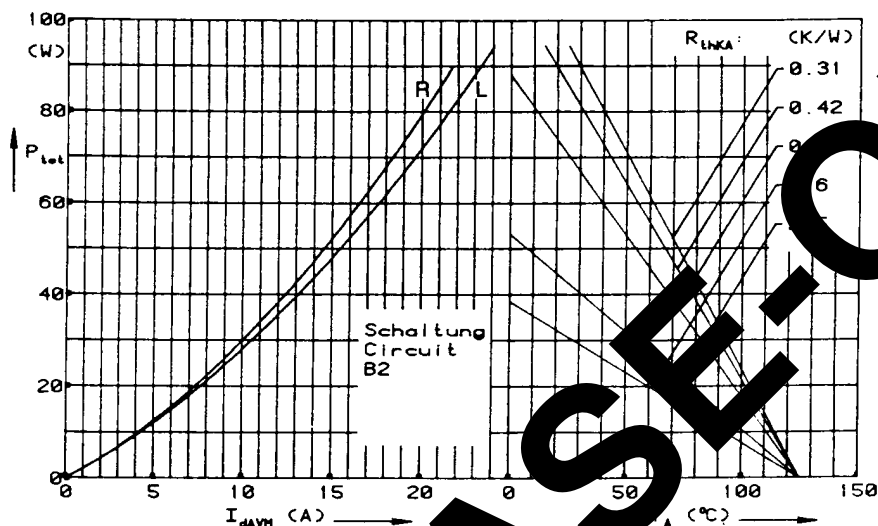


Fig. 6 Power dissipation versus direct output current and ambient temperature

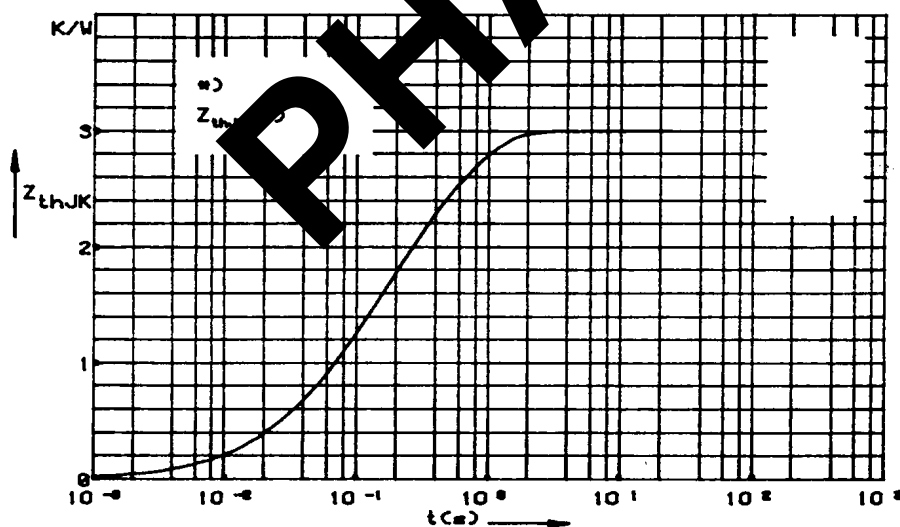


Fig. 7 Transient thermal impedance junction to heatsink per chip

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Constants for Z_{thJK} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.34	0.0344
2	1.16	0.12
3	1.5	0.5