

## **R1214Z Series**

## PWM/ VFM Step-up DC/DC Converter for White LED Applications

NO.EA-327-240404

#### **OUTLINE**

The R1214Z is a low supply current PWM/ VFM step-up DC/DC converter. Internally, the device consists of an Nch MOSFET driver, an oscillator, a PWM comparator, a voltage reference unit, an error amplifier, an overcurrent protection circuit, an under voltage lockout circuit (UVLO), an overvoltage protection circuit (LxOVP, LEDOVP), a thermal shutdown protection circuit and 2-channel current drivers for white LEDs.

The R1214Z requires minimal external component count. By simply using an inductor, a resistor, capacitors and a diode, the white LEDs can be driven with constant current and high efficiency. The LED current can be determined by the value of current setting resistor. The brightness of the LEDs can be adjusted quickly by applying a 200 Hz to 300 kHz PWM signal to the PWM pin.

The R1214Z provides the PWM control or the PWM/VFM auto switching control. The PWM control switches at fixed frequency rate in low output current in order to reduce noise. Likewise, the PWM/VFM auto switching control automatically switches from PWM mode to VFM mode in low output current in order to achieve high efficiency. Our unique control method can suppress a ripple voltage in the VFM mode, thus the R1214Z can achieve both low ripple voltage at light load and high efficiency.

The R1214Z provides an overcurrent protection circuit to limit the Lx peak current, an UVLO circuit to prevent the malfunction of the device at low input voltage, a  $L_X$ OVP circuit to monitor the excess  $L_X$  voltage, a LEDOVP circuit to monitor the excess LED1-2 voltage and a thermal shutdown protection circuit to detect the overheating of the device and stops the operation to protect the device from damage.

The R1214Z is offered in a 9-pin WLCSP-9-P1 package.

#### **FEATURES**

•	Input Voltage Range (Maximum Rating) ······2.	7 V to 5.5 V (6.5 V)
•	Supply Current ······Ty	/p. 500 μA
•	Standby Current·····Ty	/p. 0.2 μA, Max. 5 μA
•	Overcurrent Protection Circuit ······Ty	/р. 1.9 A
•	Overvoltage Protection (OVP) Circuit······Ty	/p. 35 V
•	LED1-2 Current Matching Circuit ······M	ax. 0.5% (R1214Zxx1C/ D, 20 mA)
	M	ax. 1.0% (R1214Zxx1A/ B, 20 mA)
•	Oscillator Frequency ······Ty	/р. 750 kHz/ 450 kHz
•	Maximum Duty Cycle ·····Ty	/р. 96% (R1214Zx11x)
	Ty	/р. 94% (R1214Zx21x)
•	Nch ON Resistance ······Ty	$V_{\rm P}$ . 0.25 Ω ( $V_{\rm IN}$ = 3.6 V)
•	Undervoltage Lockout (UVLO) Circuit ······Ty	/p. 2.4 V
•	Thermal Shutdown Circuit ······Ty	/р. 150°C
•	LED Dimming Control·····By	y sending a 200 Hz to 300 kHz PWM signal to the PWM pin
•	Package·····W	/LCSP-9-P1

## **APPLICATION**

- White LED backlight driver for LCD displays for portable equipment
- White LED backlight driver for LCD displays for Smartphones, Tablets and Note PCs

## **SELECTION GUIDE**

The combinations of oscillator frequency, LED voltage and power controlling method are user-selectable options.

#### **Selection Guide**

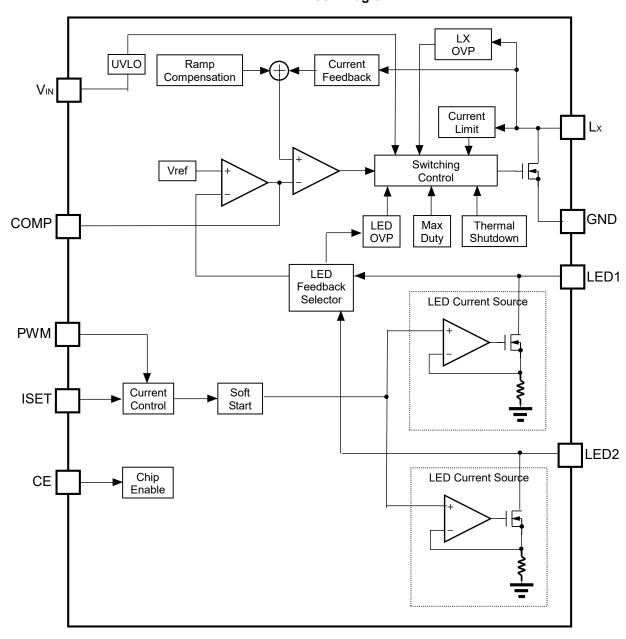
Product Name	Package	Quantity per Reel	Pb Free	Halogen Free
R1214Z2(y)1(z)-E2-F	WLCSP-9-P1	5,000 pcs	Yes	Yes

2(1/1/7)	(y): Oscillator	(z): LED Voltage	(z): Power Controlling Method
2(y)1(z)	Frequency	(I <sub>LED</sub> = 20 mA)	(2). Fower Controlling Method
211A	450 kHz	320 mV	DWM/W/SM Auto Switching
221A	750 kHz	320 1110	PWM/ VFM Auto Switching
211B	450 kHz	320 mV	PWM
211C	450 kHz	600 mV	DWM/W/SM Auto Switching
221C	750 kHz	600 1110	PWM/ VFM Auto Switching
211D	450 kHz	600 mV	PWM

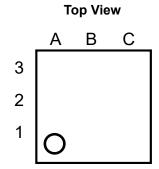
## **BLOCK DIAGRAMS**

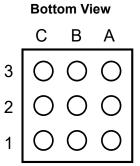
MODE

#### **R1214Z Block Diagram**



## **PIN DESCRIPTION**





**WLCSP-9-P1 Pin Configurations** 

**WLCSP-9-P1 Pin Description** 

Pin No.	o. Symbol Description	
A1 ISET LED Current Control Pin		LED Current Control Pin
A2	LED1	LED Current Supply Pin 1
A3	LED2	LED Current Supply Pin 2
B1	PWM	PWM Dimming Control Input Pin
B2	COMP	Error Amplifier Output Pin
B3	GND	Ground Pin
C1	CE	Chip Enable Pin, Active-high
C2 V <sub>IN</sub> Analog Input Voltage Pin		Analog Input Voltage Pin
C3	L <sub>X</sub>	Switching Pin, Open Drain Output

#### ABSOLUTE MAXIMUM RATINGS

**Absolute Maximum Ratings** 

(GND = 0 V)

Symbol	Item	Rating	Unit
Vin	V <sub>IN</sub> Pin Voltage	-0.3 to 6.5	V
V <sub>CE</sub>	CE Pin Voltage	-0.3 to 6.5	V
VISET	ISET Pin Voltage	-0.3 to 6.5	V
V <sub>COMP</sub>	COMP Pin Voltage	-0.3 to 6.5	V
V <sub>LX</sub>	L <sub>x</sub> Pin Voltage <sup>(1)</sup>	-0.3 to 41.5	V
$V_{PWM}$	PWM Pin Voltage	-0.3 to 6.5	V
$V_{LED}$	LED1, LED2 Pin Voltage	-0.3 to 6.5	V
P <sub>D</sub>	Power Dissipation (High Wattage Land Pattern) (2)	1190	mW
Tj	Junction Temperature Range	-40 to 125	°C
Tstg	Storage Temperature Range	−55 to 125	°C

#### **ABSOLUTE MAXIMUM RATINGS**

Electronic and mechanical stress momentarily exceeded absolute maximum ratings may cause the permanent damages and may degrade the life time and safety for both device and system using the device in the field. The functional operation at or over these absolute maximum ratings are not assured.

#### RECOMMENDED OPERATING CONDITONS

Symbol	Item	Rating	Unit
VIN	Input Voltage	2.7 to 5.5	V
Та	Operating Temperature Range	-40 to 85	°C

#### **RECOMMENDED OPERATING CONDITIONS**

All of electronic equipment should be designed that the mounted semiconductor devices operate within the recommended operating conditions. The semiconductor devices cannot operate normally over the recommended operating conditions, even if when they are used over such ratings by momentary electronic noise or surge. And the semiconductor devices may receive serious damage when they continue to operate over the recommended operating conditions.

 $<sup>^{(1)}</sup>$  Constantly applying a constant-voltage higher than 6.5 V to the  $L_X$  pin from the outside may cause the permanent damages to the device.

<sup>(2)</sup> Refer to POWER DISSIPATION for detailed information.

## **ELECTRICAL CHARACTERISTICS**

The specifications surrounded by  $\square$  are over  $-40^{\circ}$ C  $\leq$  Ta  $\leq$  85 $^{\circ}$ C.and guaranteed by design engineering.

R1214Z	Electrical Characteristics		(Ta =	: 25°C)

Symbol	Item	Condi	tions	Min.	Тур.	Max.	Unit
I <sub>DD</sub>	Supply Current	V <sub>IN</sub> = 3.6 V, no load	I, non-switching		0.5		mA
Istandby	Standby Current	$V_{IN} = 5.5 \text{ V}, V_{CE} = 0$	) V		0.2	5.0	μA
V <sub>UVLO1</sub>	UVLO Detector Threshold	V <sub>IN</sub> falling		2.25	2.4		V
V <sub>UVLO2</sub>	UVLO Released Voltage	V <sub>IN</sub> rising			V <sub>UVLO1</sub> +0.1	2.65	V
V <sub>CEH</sub>	CE Input Voltage "H"	V <sub>IN</sub> = 5.5 V		1.5			V
VCEL	CE Input Voltage "L"	$V_{IN} = 2.7 V$				0.4	V
RCE	CE Pull-down Resistance	V <sub>IN</sub> = 5.5 V			1200		ΚΩ
R <sub>PWM</sub>	PWM Pull-down Resistance	V <sub>IN</sub> = 5.5 V			1200		ΚΩ
	LED4 0 0	$R_{ISET} = 30.1 \text{ k}\Omega$	R1214Zxx1A/ B	19.6	20	20.4	
I <sub>LED</sub>	LED1-2 Current Accuracy	(1  string = 20  mA) $V_{IN} = 3.6 \text{ V}$	R1214Zxx1C/ D	19.7	20	20.3	mA
		$R_{ISET} = 30.1 \text{ k}\Omega$	R1214Zxx1A/ B		0.2	1.0	
I <sub>LEDM1</sub>	LED1-2 Current Matching Accuracy 1 (1 string = 20 mA)	PWMduty = 100% $V_{IN} = 3.6 \text{ V}$ $(I_{MAX} - I_{Ave}^{(1)}) / I_{Ave}$	R1214Zxx1C/ D		0.1	0.5	%
		$R_{ISET} = 30.1 \text{ k}\Omega$	R1214Zxx1A/ B		0.5		
ILEDM2	LED1-2 Current Matching Accuracy 2 (1 string = 20 mA)	PWMduty = 10% $(f_{PWM} = 20 \text{ kHz})$ $V_{IN} = 3.6 \text{ V}$ $(I_{MAX} - I_{Ave}) / I_{Ave}$	R1214Zxx1C/ D		0.3		%
ILEDMAX	LED1-2 Maximum Current at 100% Dimming Range	V <sub>IN</sub> = 3.6 V		40			mA
I <sub>LEDLEAK</sub>	LED1-2 Leakage Current	V <sub>IN</sub> = 5.5 V, V <sub>LED1-2</sub>	= 1 V, V <sub>CE</sub> = 0 V			3.0	μA
Ron	Nch ON Resistance	V <sub>IN</sub> = 3.6 V, I <sub>LX</sub> = 10	00 mA		0.25		Ω
ILXLEAK	Lx Leakage Current	$V_{IN} = 5.5 \text{ V}, V_{LX} = 4$	1 V			3.0	μA
I <sub>LXLIM</sub>	Lx Current Limit	V <sub>IN</sub> = 3.6 V		1.3	1.9	2.5	Α
\/. ==	LED1 2 Populated Voltage	R1214Zxx1A/ B (1 V <sub>IN</sub> = 3.6 V	string = 20 mA),		320		- mV
VLED	LED1-2 Regulated Voltage	R1214Zxx1C/ D (1 V <sub>IN</sub> = 3.6 V	string = $20 \text{ mA}$ ),		600		IIIV
fosc	Oscillator Frequency	R1214Zx11x, V <sub>IN</sub> =	3.6 V	400	450	500	       
1050	Oscillator i requericy	R1214Zx21x, V <sub>IN</sub> =	R1214Zx21x, V <sub>IN</sub> = 3.6 V		750	825	kHz

<sup>(1)</sup> I<sub>Ave</sub> is the average current of LED1-2.

## **ELECTRICAL CHARACTERISTICS (continued)**

The specifications surrounded by are over −40°C ≤ Ta ≤ 85°C.and guaranteed by design engineering.

#### **R1214Z Electrical Characteristics**

(Ta = 25°C)

Symbol	Item	Cond	litions	Min.	Тур.	Max.	Unit
Massalutus	Maximum Duty Cycle	R1214Zx11x, V <sub>IN</sub>	= 3.6 V	92	96		0/
Maxduty	Maximum Duty Cycle	R1214Zx21x, V <sub>IN</sub> = 3.6 V		91	94		%
V <sub>OVP1</sub>	V <sub>LX</sub> OVP Detector Threshold	V <sub>OUT</sub> rising V <sub>IN</sub> = 3.6 V	R1214Z2x1x	29	35	41	٧
V <sub>OVP2</sub>	V <sub>LED</sub> OVP Detector Threshold	$V_{\text{LED1-2}}$ rising, $V_{\text{IN}}$	= 3.6 V	4.3	4.5	4.7	V
tstart	Soft Start Time	V <sub>IN</sub> = 3.6 V			15		ms
T <sub>TSD</sub>	Thermal Shutdown Temperature	V <sub>IN</sub> = 3.6 V			150		°C
T <sub>TSR</sub>	Thermal Shutdown Release Temperature	V <sub>IN</sub> = 3.6 V			125		°C

All test items listed under ELECTRICAL CHARACTERISTICS are done under the pulse load condition (Tj  $\approx$  Ta = 25°C) except LED1-2 Current max at 100% Dimming Range.

#### THEORY OF OPERATION

#### **Soft-Start**

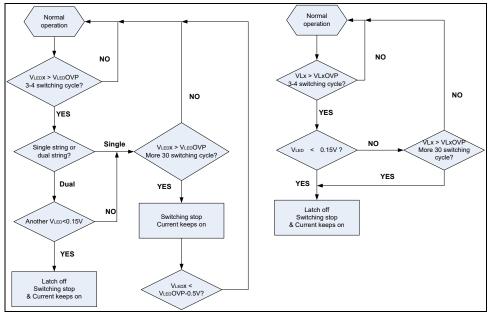
During start-up, soft-start increases the output voltage ( $V_{OUT}$ ) by forcibly switching the Lx pin and gradually increasing the Lx current limit ( $I_{LXLIM}$ ). If the preset LED current is 1.5 mA or more, soft-start gradually increases the LED current ( $I_{LED}$ ) until it reaches the preset LED current. If the preset LED current is less than 1.5 mA, soft-start increases  $I_{LED}$  until it reaches 1.5 mA, then reduces it to the preset LED current. To minimize the overshoot of  $I_{LED}$ , a 1- $\mu$ F capacitor (C4: a capacitor between COMP pin and GND) can be used. However, if C4 = 1  $\mu$ F, soft-start time (From the time CE pin changes from "L" to "H" to the time COMP pin voltage rises and be stable) becomes longer than typical application.

#### **Overcurrent Protection**

If the peak inductor current (ILmax) exceeds I<sub>LXLIM</sub>, overcurrent protection turns the driver off and turns it on in every switching cycle to continually monitor the driver current.

#### **Overvoltage Protection (OVP)**

The flow chart below illustrates the functions of LxOVP and LEDOVP. LxOVP protects the device from high voltage due to the disconnection of white LED string. To release the latch-type LxOVP or LEDOVP, set the CE pin low or decrease the V<sub>IN</sub> pin voltage below the UVLO detector threshold.



**LxOVP and LEDOVP Function Flow** 

#### **Under Voltage Lockout (UVLO)**

UVLO stops the device operation to prevent malfunction when the input  $(V_{\text{IN}})$  voltage falls below the UVLO detector threshold.

#### **Thermal Shutdown**

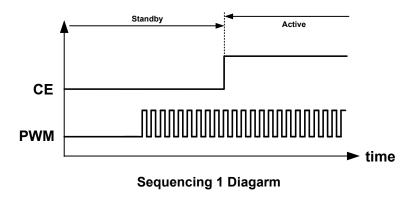
Thermal shutdown circuit detects overheating of the converter and stops the device operation to protect it from damage. If the junction temperature of the device exceeds the specified temperature, the thermal shutdown stops the device operation and resumes the device operation if the junction temperature decreases below the thermal shutdown release temperature.

#### **Input Signal Sequencing**

The timing of turning on or off of LEDs can be controlled by sequencing the input signals. There are two ways of sequencing the input signals:

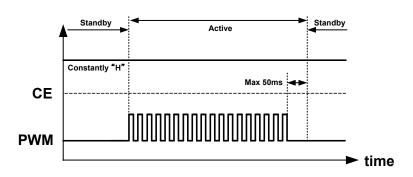
#### Sequencing 1. Send a signal to the PWM pin first and then switch the CE pin to high.

The device shifts from standby mode to active mode to turn the LEDs on.



#### Sequencing 2. Send a signal to the PWM pin while the CE pin is constantly set high.

The device shifts from standby mode to active mode to turn the LEDs on. If a signal is not sent to the PWM pin more than 50 ms (Max.), the device shifts from active mode to standby mode to turn the LEDs off.



Sequencing 2 Diagarm

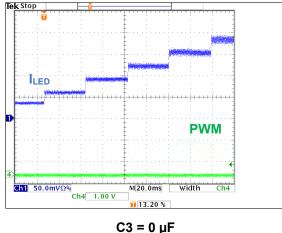
#### **LED Dimming Control**

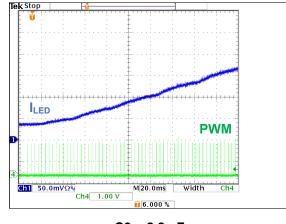
The brightness of the LEDs can be adjusted by applying a PWM signal to the PWM pin. The LED current (ILED) can be controlled by the duty of a PWM signal for the PWM pin. The duty range of a PWM signal can be set in a range of 0.4% to 100% when using a 1- $\mu$ F capacitor (C4) and a 30.1- $k\Omega$  feedback resistor (R<sub>ISET</sub>). The relation between the high-duty of the PWM pin (Hduty) and ILED can be calculated as follows:

 $I_{LED} = Hduty \times I_{LEDSET}$ 

The frequency of a PWM signal for dimming the LEDs can be set within the range of 200 Hz to 300 kHz; however, it is recommended that a 20-kHz to 100-kHz frequency be used. In the case of using a less than 20kHz PWM signal, an increase or decrease in an inductor current (IL) may generate noise in the audible band. To avoid this, connect a 2.2-µF or more capacitor (C3) between the ISET pin and GND pin. In the case of using a 20-kHz or more PWM signal, C3 is not required. Note that if a PWM signal is changed stepwise, a change in the LED luminance level can be visible as shown in the following figure. To reduce the visible change in the LED luminance level, C3 can also be used.

#### Reducing the visible change in LED luminance level by using C3





 $C3 = 2.2 \mu F$ 

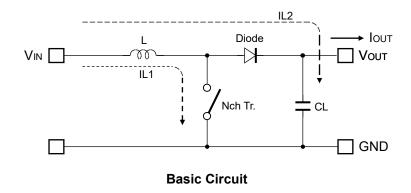
#### White LED Current Setting

The LED current for each LED string when a PWM signal applied to the PWM pin is Duty = 100% (I<sub>LEDSET</sub>) can be determined by the value of feedback resistor (RISET). ILEDSET can be calculated as follows:

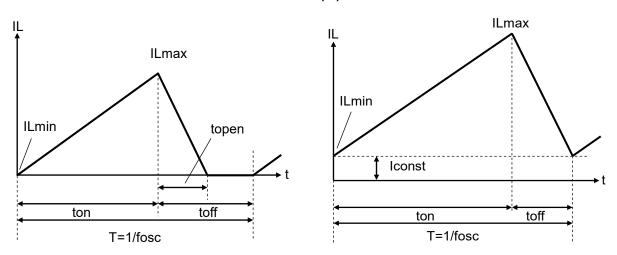
 $I_{LEDSET} = 0.0466 \times R_{ISET} / (40 \times R_{ISET})$ 

RISET should be set to 19 k $\Omega$  or more. If RISET with 30.1 k $\Omega$  is placed between the ISET and GND pins, ILEDSET will be set to 20 mA.

#### Operation of Step-Up Dc/Dc Converter And Output Current



#### **Inductor Current (IL) Waveform**



**Discontinuous Inductor Current Mode** 

#### **Continuous Inductor Current Mode**

The PWM control type of the step-up DC/DC converter has two operation modes characterized by the continuity of inductor current: discontinuous inductor current mode and continuous inductor current mode.

When an Nch transistor is in On-state, the voltage to be applied to the inductor (L) is described as  $V_{IN}$ . An increase in the inductor current (IL1) can be written as follows:

$$IL1 = V_{IN} x ton / L$$
 Equation 1

In the step-up DC/DC converter circuit, the energy accumulated during the On-state is transferred into the capacitor even in the Off-state. A decrease in the inductor current (IL2) can be written as follows:

$$IL2 = (V_{OUT} - V_{IN}) x \text{ topen } / L$$
 Equation 2

In the PWM control, IL1 and IL2 become continuous when topen = toff, which is called continuous inductor current mode.

When the device is in continuous inductor current mode and operates in steady-state conditions, the variations of IL1 and IL2 are same:

 $V_{IN} x ton / L = (V_{OUT} - V_{IN}) x toff / L$  Equation 3

Therefore, the duty cycle in continuous inductor current mode is:

duty (%)= ton / (ton + toff) =  $(V_{OUT} - V_{IN}) / V_{OUT}$  Equation 4

When topen = toff, the average of IL1 is:

IL1 (Ave.) = V<sub>IN</sub> x ton / (2 x L) ...... Equation 5

If the input voltage  $(V_{IN})$  is equal to the output voltage  $(V_{OUT})$ , the output current  $(I_{OUT})$  is:

 $I_{OUT} = V_{IN}^2 x \text{ ton } / (2 x L x V_{OUT}).$  Equation 6

If I<sub>OUT</sub> is larger than Equation 6, the device switches to continuous inductor current mode

The peak inductor current (ILmax) is:

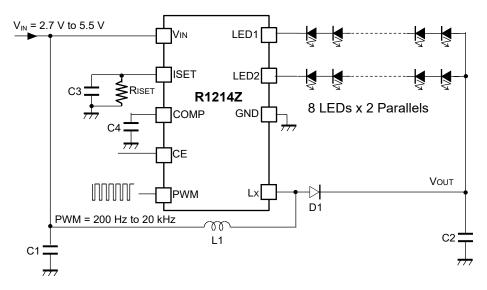
 $ILmax = I_{OUT} \times V_{OUT} / V_{IN} + V_{IN} \times T \times (V_{OUT} - V_{IN}) / (2 \times L \times V_{OUT}) \dots Equation 8$ 

As a result, ILmax becomes larger compared to  $I_{\text{OUT}}$ . The overcurrent protection circuit operates if the ILmax becomes more than the  $L_X$  current limit. When considering the input and output conditions or selecting the external components, please pay attention to ILmax.

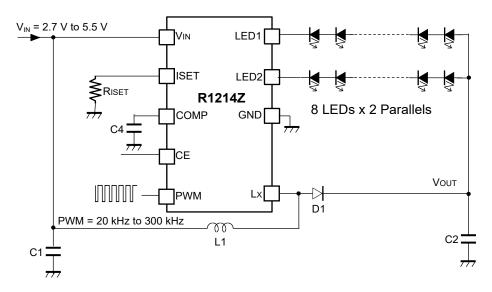
**Notes:** The above calculations are based on the ideal operation of the device. They do not include the losses caused by the external components or Nch transistor. The actual maximum output current will be 50% to 80% of the above calculation results. Especially, if IL is large or  $V_{IN}$  is low, it may cause the switching losses. An approximately 0.8 V forward voltage ( $V_F$ ) of diode should be added to  $V_{OUT}$  in the above calculations.

## **APPLICATION INFORMATION**

### **Typical Application Circuits**



Typical Application: 8 LEDs in series x 2 parallels, 200 Hz to 20 kHz PWM signal



Typical Application: 8 LEDs in series x 2 parallels, 20 kHz to 300 kHz PWM signal

#### **Recommended Inductors**

L1 (μH)	Product Name	Rated Current (mA)	Inductor Size (mm)	Components No.
10		550	2.5 x 2.0 x 1.0	VLS252010ET-100M
10	R1214Z221x	620	3.0 x 2.5 x 1.2	VLF302512MT-100M
10	(750 kHz)	900	4.0 x 3.2 x 1.2	VLF403212MT-100M
10		1320	5.0 x 4.0 x 1.2	VLF504012MT-100M
22		430	3.0 x 2.5 x 1.2	VLF302512MT-220M
22	R1214Z211x (450 kHz)	540	4.0 x 3.2 x 1.2	VLF403212MT-220M
22		890	5.0 x 4.0 x 1.2	VLF504012MT-220M

#### **Recommended Components**

Recommended components				
Symbol	Description	Rated Voltage (V)	Value	Components No.
C1 (C <sub>IN</sub> )	Ceramic Capacitor	6.3	4.7 μF or more	C1608JB0J475K
62.(6)	Caramia Canasitar	F0	2.2 µF or more R1214Z211x	C2012X5R1H225K
С2 (Соит)	Ceramic Capacitor	50	1.0 µF or more R1214Z221x	C2012X5R1H105K
C3	Ceramic Capacitor	6.3	2.2 µF or more	-
C4	Ceramic Capacitor	6.3	0.1 μF to 1μF	-
D4	B: 1	60	-	CRS12
D1	Diode	60	-	RB060M-60

#### **Cautions in Selecting External Components**

#### **Selection of Inductor**

The peak inductor current (ILmax) under steady operation can be calculated as follows:

$$ILmax = 1.25 x I_{LED} x V_{OUT} / V_{IN} + 0.5 x V_{IN} x (V_{OUT} - V_{IN}) / (L x V_{OUT} x fosc)$$

When starting up the device or adjusting the brightness of LED lights using the PWM pin, a large transient current may flow into an inductor (L1). ILmax should be equal or smaller than the Lx current limit ( $I_{LXLIM}$ ) of the device. It is recommended that a 10  $\mu$ H to 22  $\mu$ H inductor be used.

#### **Selection of Capacitor**

Set a 4.7 µF or more input capacitor (C1) between the V<sub>IN</sub> and GND pins as close as possible to the pins.

Set a 2.2 μF or more output capacitor (C2) between the V<sub>OUT</sub> and GND pins for R1214Zx11x.

Set a 1 μF or more output capacitor (C2) between the V<sub>OUT</sub> and GND pins for R1214Zx21x.

If a PWM input signal is within the range of 200 Hz to 20 kHz, set a 2.2  $\mu$ F or more capacitor (C3) between the ISET and GND pins. If a PWM input signal is within the range of 20 kHz to 300 kHz, a capacitor (C3) is not required. Set a capacitor (C4) 0.1  $\mu$ F between the COMP and GND pins.

As for the R1214Z211A and R1214Z211C, when the PWM dimming control frequency is low (ex. 1 kHz) and low on duty (ex. 10%), if Lx OVP is detected, the protection delay time may be longer than normal condition and the Lx voltage may exceed the absolute maximum rating. To avoid this condition, set C4 as 1  $\mu$ F, then the Lx voltage after detecting OVP can be suppressed. However, the soft start time will be much longer than 15 ms (typical value of the soft start time with C4 = 0.1  $\mu$ F).

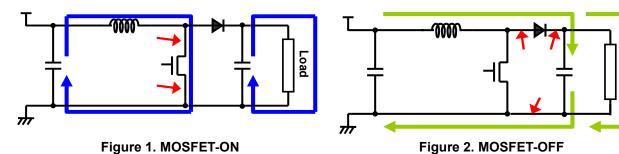
#### Selection of SBD (Schottky Barrier Diode)

Choose a diode that has low forward voltage ( $V_F$ ), low reverse current ( $I_R$ ), and low parasitic capacitance. SBD is an ideal type of diode for R1214Z since it has low  $V_F$ , low  $I_R$ , and low parasitic capacitance.

#### **TECHNICAL NOTES**

The performance of a power source circuit using this device is highly dependent on a peripheral circuit. A peripheral component or the device mounted on PCB should not exceed a rated voltage, a rated current or a rated power. When designing a peripheral circuit, please be fully aware of the following points.

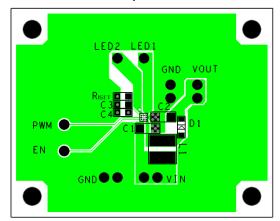
- Place an input capacitor (C1) between the V<sub>IN</sub> pin and the GND pin as close as possible. Also, connect
  the GND pin to the wider plane.
- Make the L<sub>X</sub> land pattern as small as possible.
- Make the wirings between the L<sub>X</sub> pin, the inductor and the diode as short as possible. Also, connect an output capacitor (C2) as close as possible to the cathode of the diode.
- Place C2 as close as possible to the GND pin.
- Unused LED pin should be connected to GND.
- Figure 1 and Figure 2 show the current pathways of application circuits when MOSFET is turned ON or when MOSFET is turned OFF, respectively. As shown in Figure 1 and Figure 2, the currents flow in the directions of blue or green arrows. The parasitic components, such as impedance, inductance or capacitance, formed in the pathways indicated by the red arrows affect the stability of the system and become the cause of noise. Reduce the parasitic components as much as possible. The current pathways should be made by short and thick wirings.



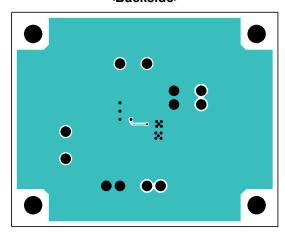
## **Reference PCB Layouts**

### R1214Z (WLCSP-9-P1) PCB Layout

### <Topside>



#### <Backside>



#### TYPICAL CHARACTERISTICS

Note: Typical Characteristics are intended to be used as reference data; they are not guaranteed.

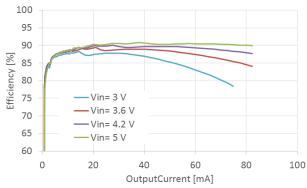
#### 1) Efficiency vs. Output Current

#### 1-1) Efficiency of R1214Z211A with Different Input Voltages VLF403012-100M/ 6s2p LEDs

 $(V_{OUT} = 16.9 \text{ V at } 40 \text{ mA per } 1 \text{ String})$ 95 90 **≥** 85 Efficiency 80 75 Vin= 3 V Vin= 3.6 V 70 -Vin= 4.2 V 65 Vin= 5 V 60 0 20 60 80 100

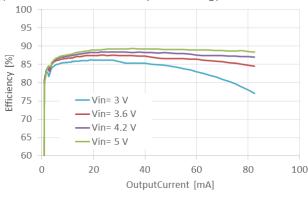
OutputCurrent [mA]

VLF403012-220M/ 6s2p LEDs  $(V_{OUT} = 16.9 \text{ V at } 40 \text{ mA per } 1 \text{ String})$ 

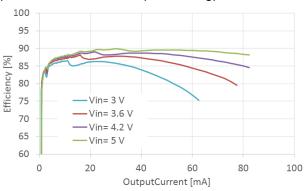


VLF403012-100M/ 8s2p LEDs

(V<sub>OUT</sub> = 22.3 V at 40 mA per 1 String)



VLF403012-220M/ 8s2p LEDs  $(V_{OUT} = 22.3 \text{ V at } 40 \text{ mA per } 1 \text{ String})$ 



#### 1-2) Efficiency of R1214Z211A with Different Inductors (V<sub>OUT</sub> = 28 V at 80 mA)

VLF504012-100M

VI F403212-100M

VLF302512-100M

80

60

OutputCurrent [mA]

 $V_{IN} = 3.6 \text{ V/ } 6s2p \text{ LEDs}$ 

75

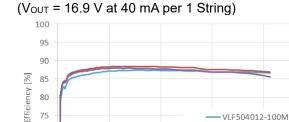
70

65

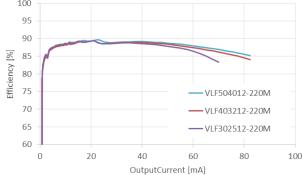
60

0

20



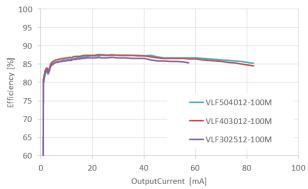
 $V_{IN} = 3.6 \text{ V/ } 6s2p \text{ LEDs}$  $(V_{OUT} = 16.9 \text{ V at } 40 \text{ mA per } 1 \text{ String})$ 100



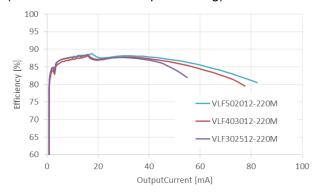
100

V<sub>IN</sub> = 3.6 V/ 8s2p LEDs

(V<sub>OUT</sub> = 22.3 V at 40 mA per 1 String)



V<sub>IN</sub> = 3.6 V/ 8s2p LEDs (V<sub>OUT</sub> = 22.3 V at 40 mA per 1 String)



#### 2) PWM Dimming Duty vs. $I_{LED}$ ( $R_{ISET}$ = 30.1 k $\Omega$ )

 $V_{IN}$  = 3.6 V/ 8s2p LEDs

 $(f_{PWM} = 20 \text{ kHz})$ 

 $(R_{ISET} = 30.1 \text{ k}\Omega)$ 



 $V_{IN} = 3.6 \text{ V/ } 8s2p \text{ LEDs}$   $(f_{PWM} = 20 \text{ kHz})$ 

 $(R_{ISET} = 30.1 \text{ k}\Omega)$ 

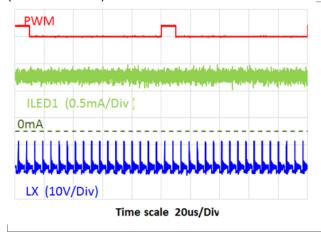


### 3) $I_{\text{LED}}$ Waveform in the VFM Mode

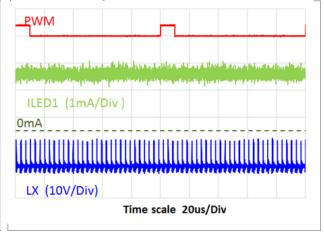
 $V_{IN} = 3.6 \text{ V/ } 8s2p \text{ LEDs}$ 

R1214Z211A (f<sub>PWM</sub> = 10 kHz, PWMduty = 10%)

 $(R_{ISET} = 30.1 \text{ k}\Omega)$ 



 $V_{IN}$  = 3.6 V/ 8s2p LEDs R1214Z221A (f<sub>PWM</sub> = 10 kHz, PWMduty = 10%) (R<sub>ISET</sub> = 30.1 k $\Omega$ )

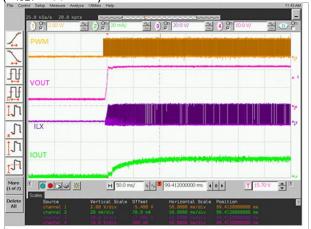


#### 4) Startup/ Shutdown Waveform

 $V_{IN} = 3.6 \text{ V/ } 8s2p \text{ LEDs}$ 

R1214Zxxxx ( $f_{PWM} = 20 \text{ kHz}$ , PWMduty = 50%)

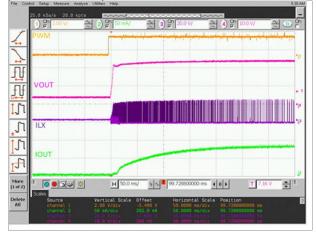
 $(R_{ISET} = 30.1 \text{ k}\Omega)$ 



V<sub>IN</sub> = 3.6 V/ 8s2p LEDs

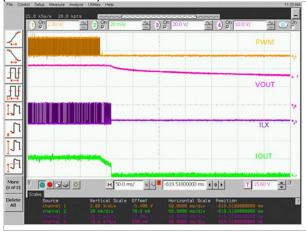
R1214Zxxxx ( $f_{PWM}$  = 20 kHz, PWMduty = 100%)

 $(R_{ISET} = 30.1 \text{ k}\Omega)$ 



 $V_{IN}$  = 3.6 V/ 8s2p LEDs R1214Zxxxx (f<sub>PWM</sub> = 20 kHz, PWMduty = 50%)

 $(R_{ISET} = 30.1 \text{ k}\Omega)$ 



V<sub>IN</sub> = 3.6 V/ 8s2p LEDs

R1214Zxxxx (f<sub>PWM</sub> = 20 kHz, PWMduty = 100%)

 $(R_{ISET} = 30.1 \text{ k}\Omega)$ 

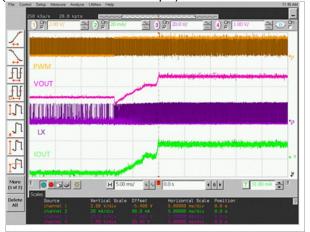


#### 5) Load Transient Response

 $V_{IN} = 3.6 \text{ V/ } 8s2p \text{ LEDs}$ 

R1214Z221A (f<sub>PWM</sub>= 20kHz, PWMduty= 10%→90%)

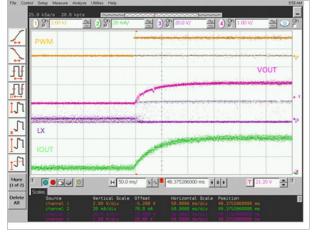
 $(R_{ISET} = 30.1 \text{ k}\Omega/C_{ISET} = 0 \mu\text{F})$ 



V<sub>IN</sub> = 3.6 V/ 8s2p LEDs

R1214Z221A (f<sub>PWM</sub>= 20kHz, PWMduty= 10%→90%)

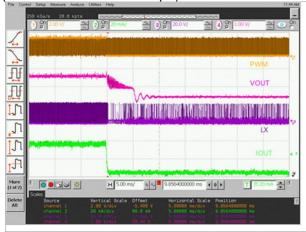
 $(R_{ISET} = 30.1 \text{ k}\Omega/C_{ISET} = 2.0 \mu\text{F})$ 



 $V_{IN}$  = 3.6 V/ 8s2p LEDs

R1214Z221A (f<sub>PWM</sub>= 20kHz, PWMduty= 90%→10%)

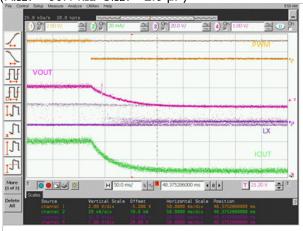
 $(R_{ISET} = 30.1 \text{ k}\Omega/C_{ISET} = 0 \mu\text{F})$ 



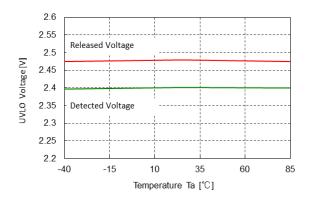
 $V_{IN} = 3.6 \text{ V/ } 8s2p \text{ LEDs}$ 

R1214Z221A (f<sub>PWM</sub>= 20kHz, PWMduty= 90%→10%)

 $(R_{ISET} = 30.1 \text{ k}\Omega/C_{ISET} = 2.0 \mu\text{F})$ 

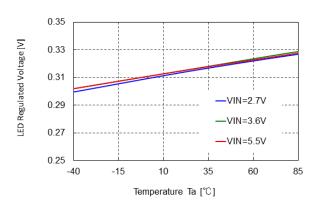


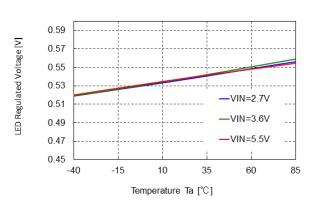
# 6) Electrical Characteristics6-1) UVLO Voltage vs. Ambient Temperature



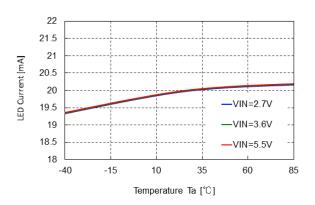
### 6-2) LED Regulated Voltage vs. Ambient Temperature

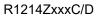
R1214ZxxxA/B R1214ZxxxC/D

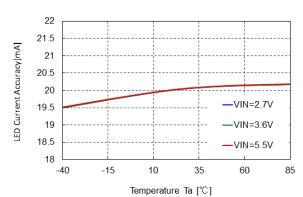




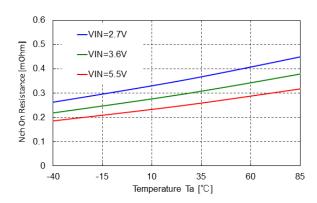
## **6-3) LED Current vs. Ambient Temperature** R1214ZxxxA/B





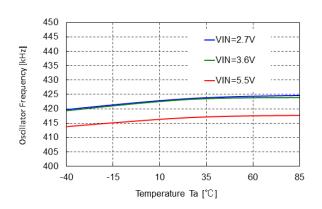


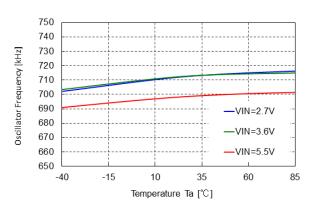
#### 6-4) Nch ON Resistance vs. Ambient Temperature



#### 6-5) Oscillator Frequency vs. Ambient Temperature

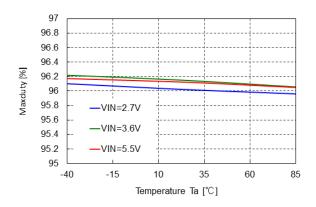
R1214Z211x R1214Z221x



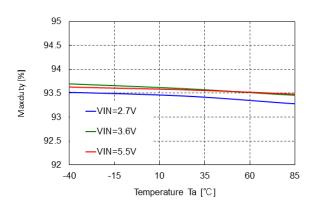


### 6-6) Maxduty vs. Ambient Temperature

R1214Z211x



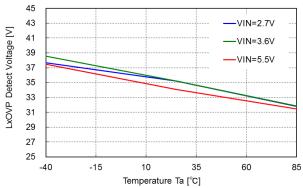
R1214Z221x

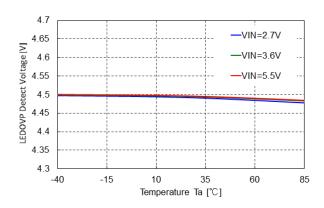


#### 6-7) LxOVP Detect Voltage vs. Ambient Temperature



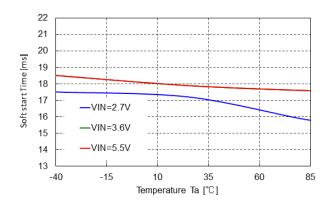
6-8) LEDOVP Detect Voltage vs. Ambient Temperature

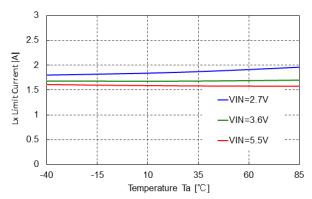




#### 6-9) Soft start Time vs. Ambient Temperature

6-10) Lx Limit Current vs. Ambient Temperature





Ver. A

The power dissipation of the package is dependent on PCB material, layout, and environmental conditions. The following conditions are used in this measurement.

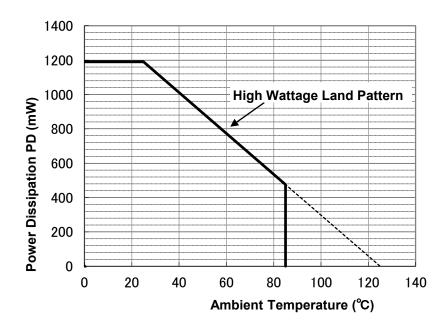
#### **Measurement Conditions**

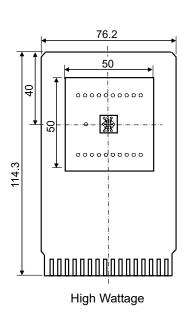
	High Wattage Land Pattern	
Environment	Mounting on Board (Wind Velocity = 0 m/s)	
Board Material	Glass Cloth Epoxy Plastic (Four-layers)	
Board Dimensions	76.2 mm × 114.3 mm × 1.6 mm	
Copper Ratio	Outer Layers (First and Fourth Layers): Approx. 60% Inner Layers (Second and Third Layers): 100%	

#### **Measurement Result**

 $(Ta = 25^{\circ}C, Tjmax = 125^{\circ}C)$ 

	High Wattage Land Pattern		
Power Dissipation	1190 mW		
Thermal Resistance	Γhermal Resistance θja = (125 − 25°C) / 1.19 W = 84°C/W		



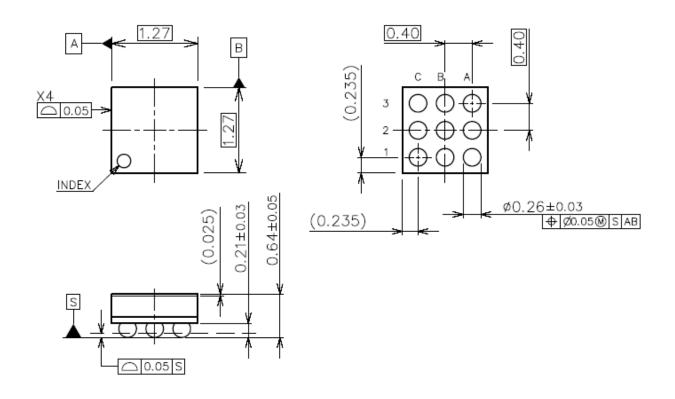


O IC Mount Area (mm)

**Power Dissipation vs. Ambient Temperature** 

**Measurement Board Pattern** 

Ver. A



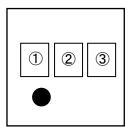
WLCSP-9-P1 Package Dimensions (Unit: mm)

PART MARKINGS R1214Z

MK-R1214Z-JE-B

1: Product Code  $\cdots$  Refer to Part Marking List

23 : Lot Number ··· Alphanumeric Serial Number



**R1214Z Part Markings** 

#### NOTICE

There can be variation in the marking when different AOI (Automated Optical Inspection) equipment is used. In the case of recognizing the marking characteristic with AOI, please contact our sales or distributor before attempting to use AOI.

**R1214Z Part Marking List** 

<b>-</b>				
Product Name	①	23		
R1214Z211A-E2-F	U	Lot No.		
R1214Z221A-E2-F	U	Lot No.		
R1214Z211B-E2-F	U	Lot No.		
R1214Z211C-E2-F	U	Lot No.		
R1214Z221C-E2-F	U	Lot No.		
R1214Z211D-E2-F	U	Lot No.		

VI-160823

No.	Inspection Items	Inspection Criteria	Figure
1	Package chipping	A≥0.2mm is rejected B≥0.2mm is rejected C≥0.2mm is rejected And, Package chipping to Si surface and to bump is rejected.	B C
2	Si surface chipping	A≥0.2mm is rejected B≥0.2mm is rejected C≥0.2mm is rejected But, even if A≥0.2mm, B≤0.1mm is acceptable.	B C
3	No bump	No bump is rejected.	
4	Marking miss	To reject incorrect marking, such as another product name marking or another lot No. marking.	
5	No marking	To reject no marking on the package.	
6	Reverse direction of marking	To reject reverse direction of marking character.	
7	Defective marking	To reject unreadable marking. (Microscope: X15/ White LED/ Viewed from vertical direction)	
8	Scratch	To reject unreadable marking character by scratch. (Microscope: X15/ White LED/ Viewed from vertical direction)	
9	Stain and Foreign material	To reject unreadable marking character by stain and foreign material. (Microscope: X15/ White LED/ Viewed from vertical direction)	

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- 2. The materials in this document may not be copied or otherwise reproduced in whole or in part without the prior written consent of us.
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  - Aerospace Equipment
  - Equipment Used in the Deep Sea
  - · Power Generator Control Equipment (nuclear, steam, hydraulic, etc.)
  - · Life Maintenance Medical Equipment
  - · Fire Alarms / Intruder Detectors
  - Vehicle Control Equipment (automotive, airplane, railroad, ship, etc.)
  - Various Safety Devices
  - Traffic control system
  - Combustion equipment

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- 6. We are making our continuous effort to improve the quality and reliability of our products, but semiconductor products are likely to fail with certain probability. In order to prevent any injury to persons or damages to property resulting from such failure, customers should be careful enough to incorporate safety measures in their design, such as redundancy feature, fire containment feature and fail-safe feature. We do not assume any liability or responsibility for any loss or damage arising from misuse or inappropriate use of the products.
- 7. The products have been designed and tested to function within controlled environmental conditions. Do not use products under conditions that deviate from methods or applications specified in this datasheet. Failure to employ the products in the proper applications can lead to deterioration, destruction or failure of the products. We shall not be responsible for any bodily injury, fires or accident, property damage or any consequential damages resulting from misuse or misapplication of the products.
- 8. Quality Warranty
  - 8-1. Quality Warranty Period
    - In the case of a product purchased through an authorized distributor or directly from us, the warranty period for this product shall be one (1) year after delivery to your company. For defective products that occurred during this period, we will take the quality warranty measures described in section 8-2. However, if there is an agreement on the warranty period in the basic transaction agreement, quality assurance agreement, delivery specifications, etc., it shall be followed.
  - 8-2. Quality Warranty Remedies
    - When it has been proved defective due to manufacturing factors as a result of defect analysis by us, we will either deliver a substitute for the defective product or refund the purchase price of the defective product.
    - Note that such delivery or refund is sole and exclusive remedies to your company for the defective product.
  - 8-3. Remedies after Quality Warranty Period
    - With respect to any defect of this product found after the quality warranty period, the defect will be analyzed by us. On the basis of the defect analysis results, the scope and amounts of damage shall be determined by mutual agreement of both parties. Then we will deal with upper limit in Section 8-2. This provision is not intended to limit any legal rights of your company.
- 9. Anti-radiation design is not implemented in the products described in this document.
- 10. The X-ray exposure can influence functions and characteristics of the products. Confirm the product functions and characteristics in the evaluation stage.
- 11. WLCSP products should be used in light shielded environments. The light exposure can influence functions and characteristics of the products under operation or storage.
- 12. Warning for handling Gallium and Arsenic (GaAs) products (Applying to GaAs MMIC, Photo Reflector). These products use Gallium (Ga) and Arsenic (As) which are specified as poisonous chemicals by law. For the prevention of a hazard, do not burn, destroy, or process chemically to make them as gas or power. When the product is disposed of, please follow the related regulation and do not mix this with general industrial waste or household waste.
- 13. Please contact our sales representatives should you have any questions or comments concerning the products or the technical information.



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