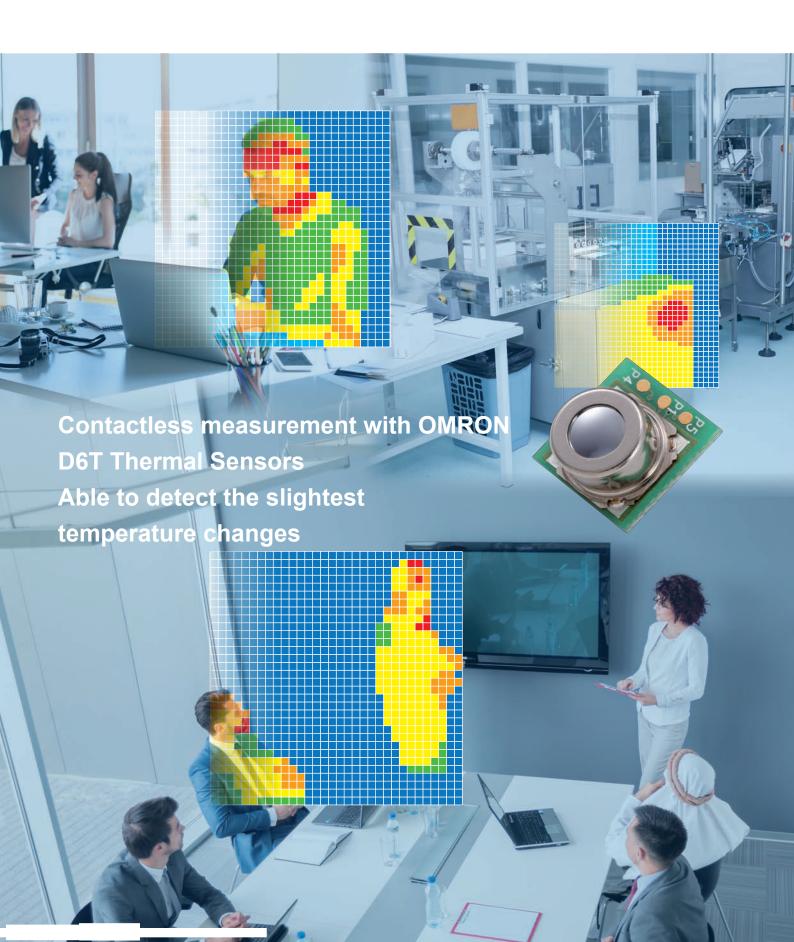
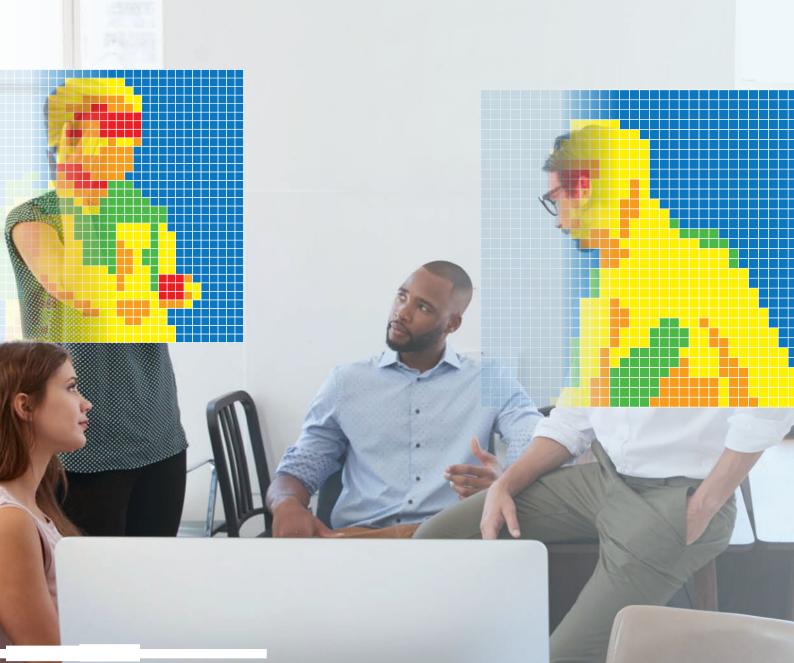
# **OMRON**

# **D6T MEMS Thermal Sensors**



# Contactless Measurement OMRON MEMS Thermal Sensors are able to detect the slightest temperature changes

MEMS Thermal (IR sensor) measures the surface temperature of objects without touching them when the thermopile element absorbs the amount of radiant energy from the object.





# **High Precision**

# Market performance of over 6 million units\*1 with a stable temperature output\*2

- \*1: According to OMRON's research as of March 2022.
- \*2: Refer to the Noise Equivalent Temperature Difference (NETD) on page 12.

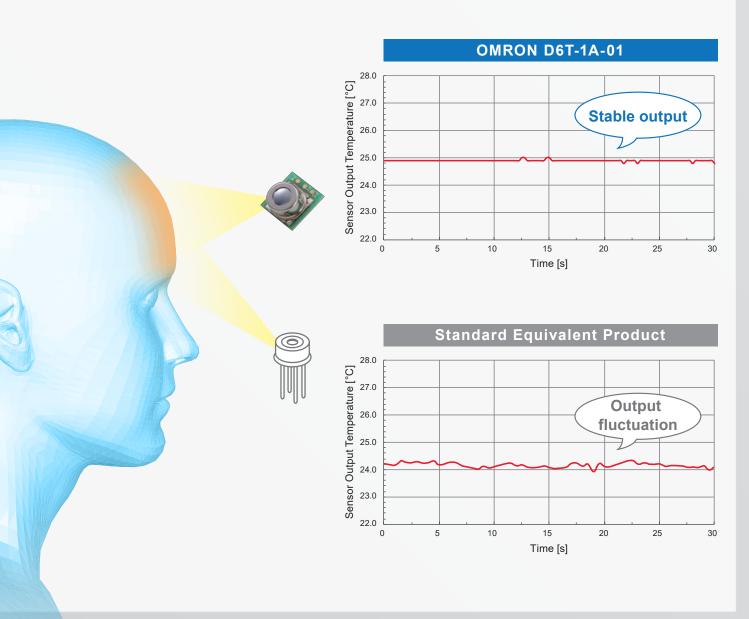
# Past problem

Output was unstable in applications requiring high precision





# Stable temperature output



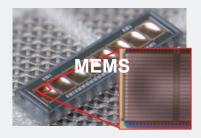
Note 1. According to OMRON's evaluation method (30-second continuous measurement with a blackbody furnace at 25°C) Note 2. However, product specifications are not quaranteed.

# -High Precision- Why?

# Achieves a low NETD\*1 through the combination of ASIC and MEMS



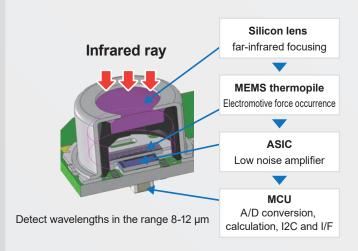




OMRON's unique digital filter and process optimization help reduce the noise of ASIC, thus achieving a low NETD\*1.

# **Product Structure**

MEMS technology allows combining thermopile elements and ASICs into one package, resulting in ultra-compact footprint and high precision.



# **■ MEMS** thermopile detection principle



The sensor utilizes the seebeck effect in which thermoelectric force is generated due to the temperature difference that occurs across the junction points of two different types of metal.

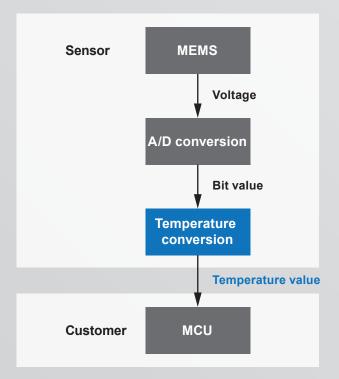
<sup>\*1:</sup> Refer to the Noise Equivalent Temperature Difference (NETD) on page 12.

# Easy connection

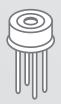
# Direct temperature value output allows easy software design

# **OMRON D6T**

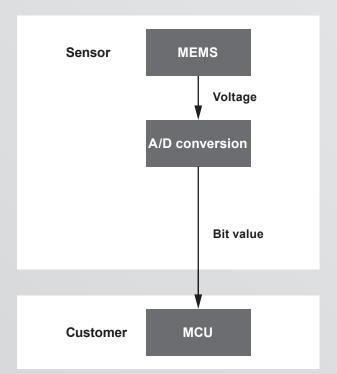




CAN packaged thermal sensor from a competitor



# Bit value output



**Provision of Development Support Tool** 

Note: 2JCIE-EV01-RP1, 2JCIE-EV01-AR1, 2JCIE-EV01-FT1, and 2JCIE-HARNESS-01 in this catalog is discontinued at the end of January 2025.

MEMS thermal sensors can be connected to **OMRON sensor evaluation boards**.

The below 3 types of platform are applicable. Evaluation can be performed easily by connecting thermal sensor, evaluation board, and harness to the platform.

Also.
-



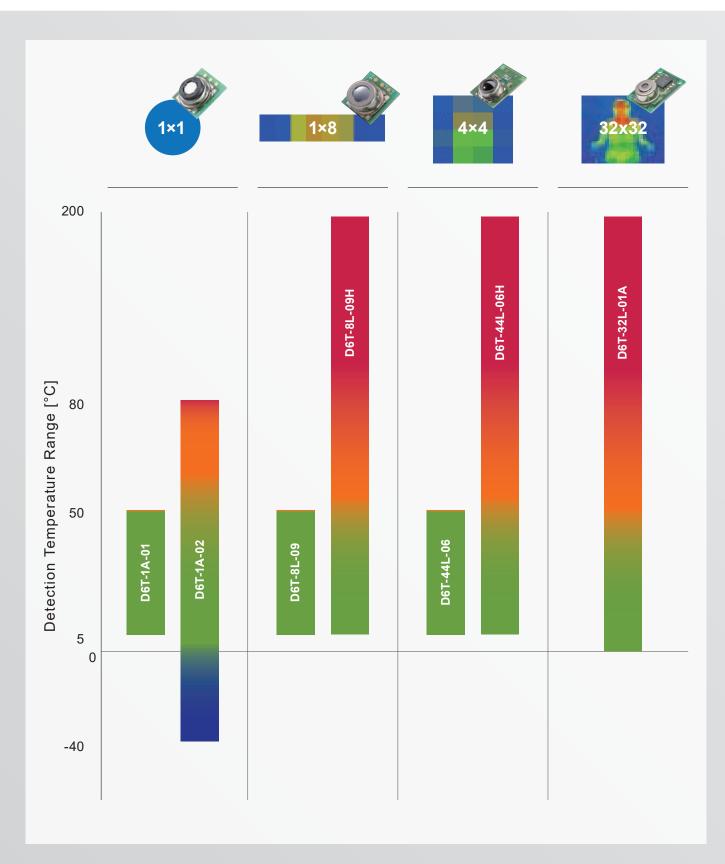


*	0			
Sensor	<b>Harness for Connection</b>	<b>Evaluation Board</b>	Platform	Sample Code
		2JCIE-EV01-RP1	Raspberry Pi *1	https://github.com/omron-devhub/d6t-2jcieev01-raspberrypi
D6T	2JCIE-HARNESS-01	2JCIE-EV01-AR1	Arduino *2	https://github.com/omron-devhub/d6t-2jcieev01-arduino
		2JCIE-EV01-FT1	ESP32 Feather *3	https://github.com/omron-devhub/d6t-2jcieev01-arduino

<sup>\*1.</sup> Raspberry Pi is a registered trademark of the Raspberry Pi Foundation. \*2. Arduino is a registered trademark of Arduino LLC and Arduino SRL. \*3. Feather is a registered trademark of Adafruit Industries LLC.

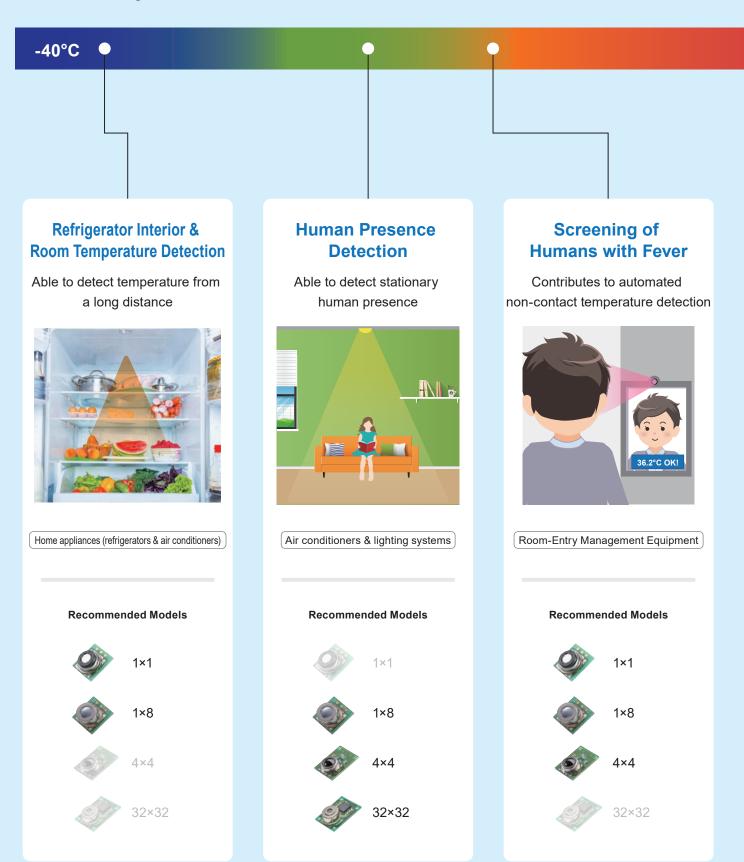
# Number of elements and temperature lineup

Variation of the number of elements (1 to 1024) and the temperature range (-40 to 200°C)



# **Example Applications**

The sensors can be used in a wide range of applications, depending on the temperature measurement range.



# 200°C

# **Abnormal High Temperature Monitoring**

Contributes to prevention of fires due to overheating



Transformers & distribution boards

# **Recommended Models**







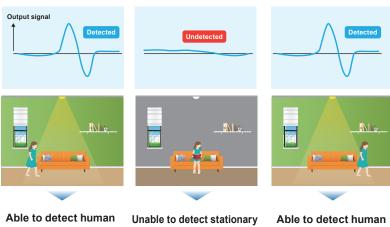


# Comparison with Pyroelectric Sensor

Both the pyroelectric sensor and non-contact MEMS thermal sensor can detect even the slightest amount of radiant energy from objects such as infrared radiation and convert them into temperature readings. However, unlike pyroelectric sensor that relies on motion detection, non-contact MEMS thermal sensor is able to detect the presence of stationary humans (or objects).

# Pyroelectric sensor

Converts temperature readings only when detecting "temperature changes in the radiant energy" in its field of view.



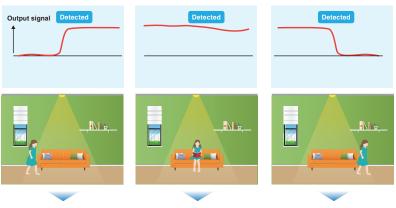
(object) motion

human (object) presence

(object) motion

# **MEMS** thermal sensor (thermopile)

Converts temperature readings by "continuously detecting the temperature of radiant energy" in its field of view



Able to detect both stationary and motion state of humans (objects).

# **Viewing Angle and Measurement Area**

Choose your preferred sensor viewing angle to meet your application needs.

Model	D6T-1A-01	D6T-1A-02	D6T-8L-09 D6T	-8L-09H	D6T-44L-06	D6T-44L-06H	D6T-32	2L-01A						
Appearance														
Number of elements	1(1	x1)	8(1x8)		16(4	x4)	1024(	32x32)						
Viewing angle X-direction Y-direction	X = 58.0° Y = 58.0°	X = 26.5° Y = 26.5°	X = 54.5° Y = 5.5°		X=44.2° Y=45.7°			00.0°						
Size of measurement area	← Distance →	X	Distance x		← Distance →		→ Distance →							
Distance 10 cm	X = 11 cm Y = 11 cm	X = 4.7 cm Y = 4.7 cm	X = 10 cm Y = 1.0 cm		X = 8. Y = 8.			20 cm 20 cm						
Distance 50 cm	X = 55 cm Y = 55 cm	X = 24 cm Y = 24 cm	X = 52 cm Y = 4.8 cm		X = 4 Y = 4			100 cm 100 cm						
Distance 1 m	X = 111 cm Y = 111 cm	X = 47 cm Y = 47 cm	X = 103 cm Y = 10 cm		X = 8 Y = 8			200 cm 200 cm						
Distance 2 m	X = 222 cm Y = 222 cm	X = 94 cm Y = 94 cm	X = 206 cm Y = 20 cm		X = 16 Y = 16			100 cm 100 cm						
Distance 3 m	X = 333 cm Y = 333 cm	X = 141 cm Y = 141 cm	X = 309 cm Y = 30 cm		X = 24 Y = 25			600 cm						

Note1: The sizes of measurement areas indicated above are for reference only.

Note2: The size of the measurement area changes according to sensor mounting angle

# D6T MEMS Thermal Sensors

# **MEMS Non-Contact Thermal Sensor** for Contactless Measurement

- Achieves a low NETD\*1 through the combination of ASIC and MEMS
- Direct temperature value output allows easy software design
- Variation of the number of elements (1 to 1024) and the temperature range (-40 to 200°C)
- \*1. Refer to the Noise Equivalent Temperature Difference (NETD) on page 12.



Refer to Safety Precautions on page 18.

# N. d. Co.

# **Ordering Information**

### Thermal Sensors

Thermal Sensors							
Element type	Model	Shape					
1×1	D6T-1A-01						
	D6T-1A-02	APT AL					
1×8	D6T-8L-09						
	D6T-8L-09H	VI. THE					
4×4	D6T-44L-06						
	D6T-44L-06H	A PARIS HER					
32×32	D6T-32L-01A	00000					

# **Model Number Legend**

D6T-<u></u>\_-<u></u>\_ <u></u>\_ <u></u>\_ (1) (2) (3)

### (1) Number of elements

1A:1(1 × 1) 8L:8(1 × 8) 44L:16(4 × 4) 32L:1024(32 × 32)

## (2) Viewing angle

01 : X direction, Y direction=58.0°
02 : X direction, Y direction=26.5°
09 : X direction=54.5°, Y direction=5.5°
06 : X direction=44.2°, Y direction=45.7°
01A : X direction, Y direction=90°

# (3) Special Functions

H : High-temperature type Non-display : Standard sensor

# Accessories (Sold separately)

Туре	Model
Cable Harness	D6T-HARNESS-02

### **Others**

MEMS thermal sensors can be connected to OMRON sensor evaluation boards.

The below 3 types of platform are applicable. Evaluation can be performed easily by connecting thermal sensor, evaluation board, and harness to the platform.

Platform	Evaluation Board	Harness for connection (Evaluation Board - D6T)	Sample Source Code
For Raspberry Pi *1	2JCIE-EV01-RP1	2JCIE-HARNESS-01	https://github.com/omron-devhub/d6t-2jcieev01-raspberrypi
For Arduino *2	2JCIE-EV01-AR1	2JCIE-HARNESS-01	https://github.com/omron-devhub/d6t-2jcieev01-arduino
For ESP32 Feather *3	2JCIE-EV01-FT1	2JCIE-HARNESS-01	https://github.com/omron-devhub/d6t-2icieev01-arduino

For details of evaluation boards and sample source codes, refer to the following website.

(https://components.omron.com/sensor/evaluation-board/2jcie)

- \*1. Raspberry Pi is a registered trademark of the Raspberry Pi Foundation.
- \*2. Arduino is a registered trademark of Arduino LLC and Arduino SRL.
- \*3. Feather is a registered trademark of Adafruit Industries LLC.

Note: 2JCIE-EV01-RP1, 2JCIE-EV01-AR1, 2JCIE-EV01-FT1, and 2JCIE-HARNESS-01 in this catalog is discontinued at the end of January 2025.

# Ratings, Specifications, and Functions

# Ratings

Item Model	D6T-1A-01	D6T-1A-02	D6T-8L-09	D6T-8L-09H	D6T-44L-06	D6T-44L-06H	D6T-32L-01A	
Power supply voltage	4.5 to 5.5 VDC							
Storage temperature range	-20 to 80°C	-40 to 80°C	-20 to	80°C	-10 to 60°C		-20 to 80°C	
Storage temperature range	(with no icing or condensation)							
Operating temperature range	0 to 60°C	-40 to 80°C	0 to 60°C		0 to 60°C		-10 to 70°C	
Operating temperature range	(with no icing or condensation)							
Storage humidity range	95% max.	95% max.	95% max. 85% max.		max.	95% max.		
Storage humidity range (with no icing or condensation)					,			
Operating by midity range	20% to 95%	20% to 95%	20% to 95% 20% to 85%		o 85%	20% to 95%		
Operating humidity range		ı	(with r	no icing or condens	sation)		ı.	

# **Characteristics**

Item	Model	D6T-1A-01	D6T-1A-02	D6T-8L-09	D6T-8L-09H	D6T-44L-06	D6T-44L-06H	D6T-32L-01A
View angle *1	X direction	58.0°	26.5°	54.5°	54.5°			90°
view arigie	Y direction	58.0°	26.5°	5.5°		45.7°		90°
Object temperature	±1.5°C max.  Measurement conditions: Vcc = 5.0 V  (1) Tx = 25°C, Ta = 25°C  (2) Tx = 45°C, Ta = 25°C  (3) Tx = 45°C, Ta = 45°C							Within ±3.0°C Measurement conditions: Vcc = 5.0 V Tx = 25°C, Ta = 25°C Central 16x16-pixel area
output accuracy *2	Accuracy 2	±3.0°C max.  Measurement conditions: Vcc = 5.0 V  (4) Tx = 25°C, Ta = 45°C						Within ±5.0°C Measurement conditions: Vcc = 5.0 V Tx = 80°C, Ta = 25°C Central 16x16- pixel area
Current consumption		3.5 mA typical		5 mA typical				19 mA typical

# **Functions**

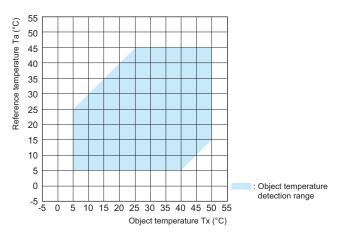
Item	Model	D6T-1A-01	D6T-1A-02	D6T-8L-09	D6T-8L-09H	D6T-44L-06	D6T-44L-06H	D6T-32L-01A	
Object temperature detection range *2		5 to 50°C	-40 to 80°C	5 to 50°C	5 to 200°C	5 to 50°C	5 to 200°C	0 to 200°C	
Ambient temperature detection range *2		5 to 45°C	-40 to 80°C	5 to 45°C	5 to 45°C	5 to 45°C	5 to 45°C	0 to 80°C	
Output specifications			t correspond to the om a serial commu		re (Tx) and referen	ce temperature			
Output form (Object temperature d	etection)	Binary code (10 ti	mes the detected	temperature (°C))	Binary code (5 times the detected temperature (°C))  Binary code (10 times the detected temperature (°C))  Binary code (10 times the detected temperature (°C))				
Output form (Reference temperature inside the sensor)  Binary code (10 times the detected temperature (°C))									
Communications form I2C compliant									
Temperature resolution (NETD) *3		0.02°C (Data update cycle 100 msec)	0.06°C (Data update cycle 100 msec)	0.03°C (Data update cycle 250 msec)	0.03°C (Data update cycle 250 msec)	0.06°C (Data update cycle 300 msec)	0.06°C (Data update cycle 300 msec)	0.33°C*4 (Data update cycle 200 msec)	

- \*1. Refer to Field of View Characteristics.
- 2. Refer to Object Temperature Detection Range.
- \*3. Reference data
- \*4. Taken to be the average value of the central 4 pixels.

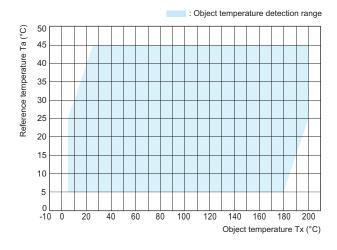
# D<sub>6</sub>T

# **Object Temperature Detection Range**

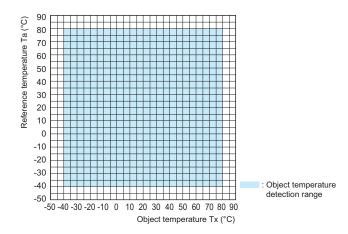
D6T-44L-06, D6T-8L-09, D6T-1A-01



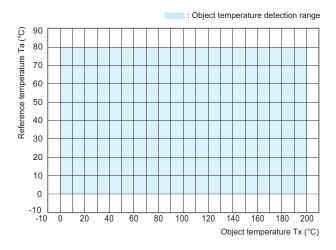
D6T-44L-06H, D6T-8L-09H



### D6T-1A-02



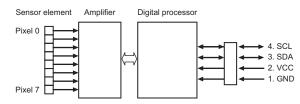
D6T-32L-01A



# **Connections**

# **Thermal Sensor Configuration Diagram**

<D6T-8L-09> <D6T-8L-09H>



Note: The D6T-44L-06 has pixels 0 to 15. The D6T-44L-06H has pixels 0 to 15. The D6T-1A-01 has pixel 0. The D6T-1A-02 has pixel 0. The D6T-32L-01A has pixel 0 to 1023.

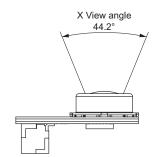
# **Terminal Arrangement**

Terminal	Name	Function	Remarks
1	GND	Ground	
2	VCC	Positive power supply voltage input	
3	SDA	Serial data I/O line	Connect the open-drain SDA terminal to a pull-up resistor.
4	SCL	Serial clock input	Connect the open-drain SCL terminal to a pull-up resistor.

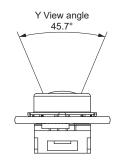
# **Field of View Characteristics**

# D6T-44L-06 D6T-44L-06H

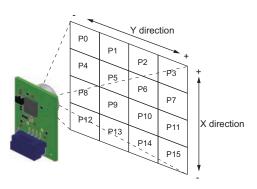
# Field of View in X Direction



### Field of View in Y Direction

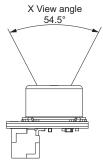


# **Detection Area for Each Pixel**

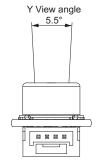


Note: Definition of view angle: Using the maximum sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the View angle.

# D6T-8L-09 D6T-8L-09H Field of View in X Direction

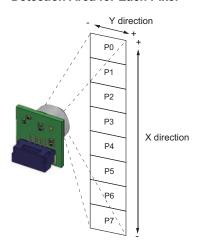


## Field of View in Y Direction

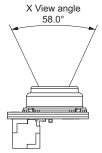


Note: Definition of view angle: Using the maximum Sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the view angle.

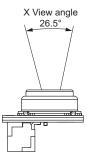
# **Detection Area for Each Pixel**



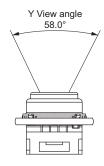
# D6T-1A-01 Field of View in X Direction



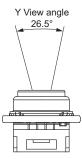
D6T-1A-02 Field of View in X Direction



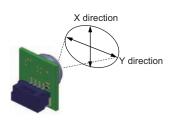
# Field of View in Y Direction



Field of View in Y Direction

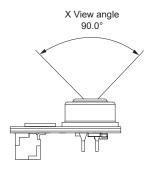




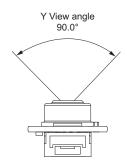


Note: Definition of view angle: Using the maximum Sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the view angle.

# D6T-32L-01A Field of View in X Direction

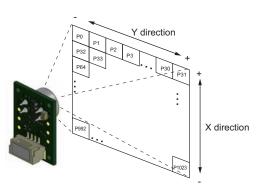


Field of View in Y Direction



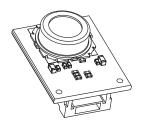
Note: Definition of view angle: Using the maximum Sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the view angle.

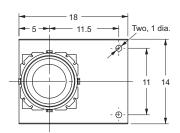
# **Detection Area for Each Pixel**

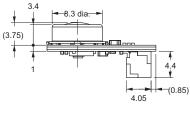


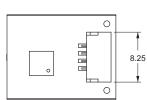
(Unit: mm)

# D6T-44L-06 D6T-44L-06H



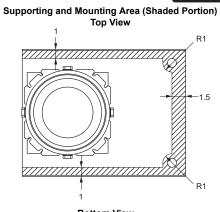




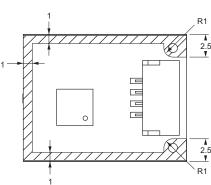




# CAD Data



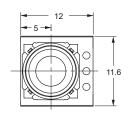
**Bottom View** 

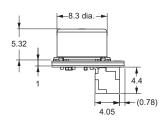


Note: Due to insulation distance limitations, do not allow metal parts to come into contact with the Sensor.

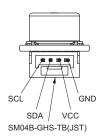
# D6T-8L-09 D6T-8L-09H





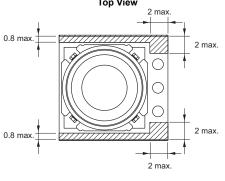




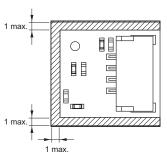


CAD Data

# Supporting and Mounting Area (Shaded Portion) Top View



### **Bottom View**

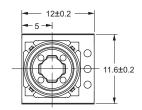


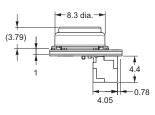
Note: Due to insulation distance limitations, do not allow metal parts to come into contact with the Sensor.

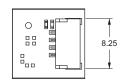
Note: Unless otherwise specified, a tolerance of  $\pm 0.3$  mm applies to all dimensions.

# D6T-1A-01 D6T-1A-02

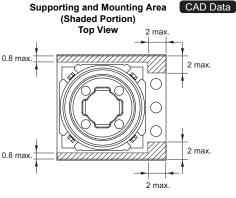


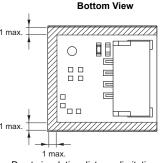




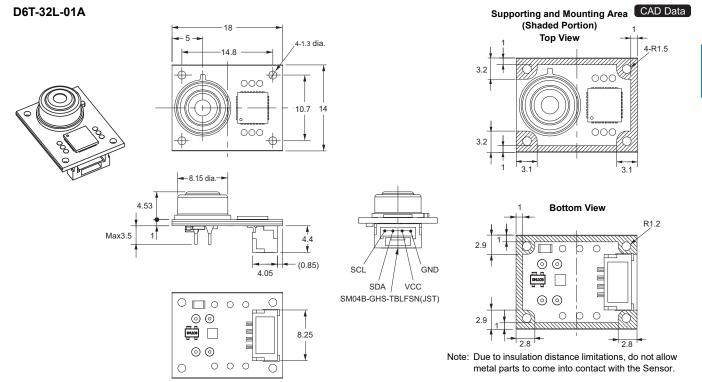






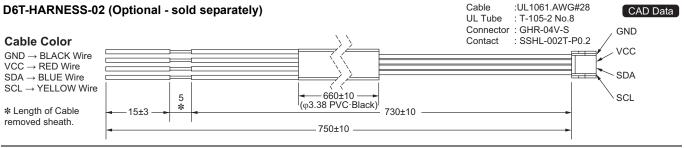


Note: Due to insulation distance limitations, do not allow metal parts to come into contact with the Sensor.



SCL

SDA VCC SM04B-GHS-TB(JST)



Note: Unless otherwise specified, a tolerance of  $\pm 0.3$  mm applies to all dimensions.

# **Safety Precautions**

### **Precautions for Correct Use**

### Installation

 The sensor may not achieve the characteristics given in this datasheet due to the ambient environment or installation location. Before using the Sensor, please acquire an adequate understanding and make a prior assessment of Sensor characteristics in your actual system.

# Operating Environment

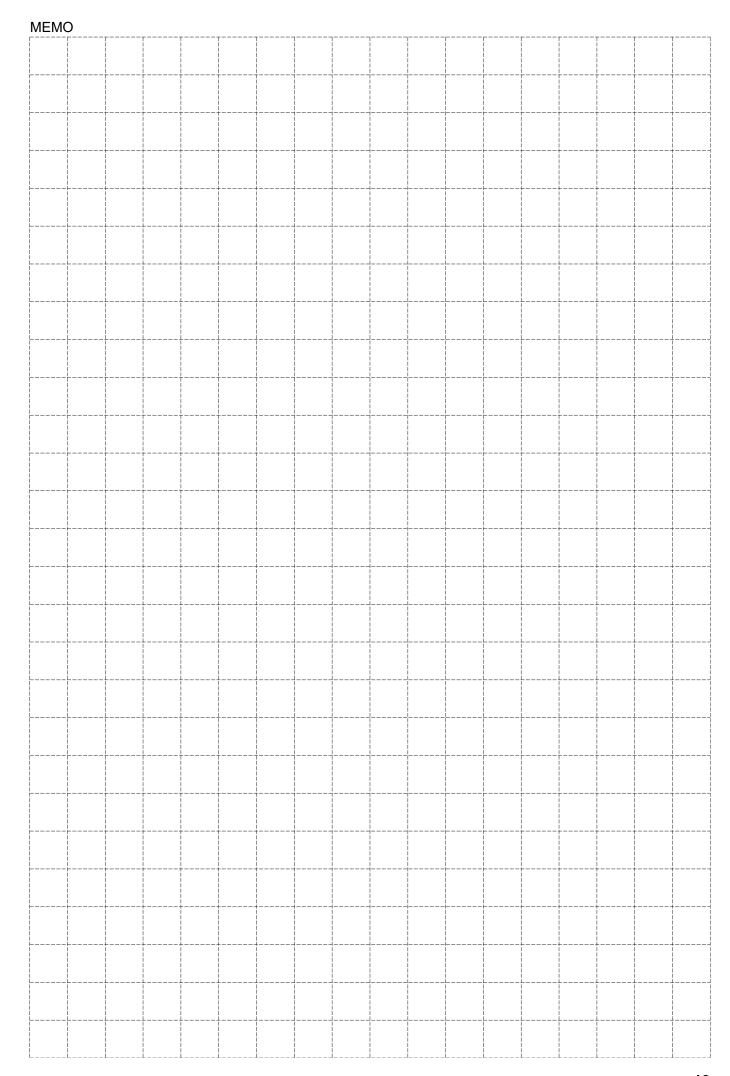
- Do not use the Sensor in locations where dust, dirt, oil, and other foreign matter will adhere to the lens. This may prevent correct temperature measurements.
- Do not use the Sensor in any of the following locations.
  - Locations where the Sensor may come into contact with water or oil
  - Outdoors
  - · Locations subject to direct sunlight.
  - Locations subject to corrosive gases (in particular, chloride, sulfide, or ammonia gases).
  - · Locations subject to extreme temperature changes
  - · Locations subject to icing or condensation.
  - · Locations subject to excessive vibration or shock.

### Noise Countermeasures

- The Sensor does not contain any protective circuits. Never subject it to an electrical load that exceeds the absolute maximum ratings for even an instance. The circuits may be damaged. Install protective circuits as required so that the absolute maximum ratings are not exceeded.
- Keep as much space as possible between the Sensor and devices that generates high frequencies (such as high-frequency welders and high-frequency sewing machines) or surges.
- Attach a surge protector or noise filter on nearby noise-generating devices (in particular, motors, transformers, solenoids, magnetic coils, or devices that have an inductance component).
- In order to prevent inductive noise, separate the connector of the Sensor from power lines carrying high voltages or large currents. Using a shielded line is also effective.
- If a switching regulator is used, check that malfunctions will not occur due to switching noise from the power supply.

# Handling

- This Sensor is a precision device. Do not drop it or subject it to excessive shock or force. Doing so may damage the Sensor or change its characteristics. Never subject the connector to unnecessary force. Do not use a Sensor that has been dropped.
- Take countermeasures against static electricity before you handle the Sensor.
- Turn OFF the power supply to the system before you install the Sensor. Working with the Sensor while the power supply is turned ON may cause malfunctions.
- Secure the Sensor firmly so that the optical axis does not move
- Install the Sensor on a flat surface. If the installation surface is not even, the Sensor may be deformed, preventing correct measurements
- Do not install the Sensor with screws. Screws may cause the resist to peel from the board. Secure the Sensor in a way that will not cause the resist to peel.
- · Always check operation after you install the Sensor.
- Use the specified connector (GHR-04 from JST) and connect it securely so that it will not come off. If you solder directly to the connector terminals, the Sensor may be damaged.
- Make sure to wire the polarity of the terminals correctly. Incorrect polarity may damage the Sensor.
- · Never attempt to disassemble the Sensor.
- · Do not use the cable harness to the other product.



# **Information of Related Products**



D6T MEMS Thermal Sensor User's Manual



D6F
MEMS Flow Sensor

Catalog No. A284-E1 Catalog No. X211-E1



**Sensor Selection Guide** 

Catalog No. Y232-E1

Please check each region's Terms & Conditions by region website.

# **OMRON Corporation**

**Device & Module Solutions Company** 

# **Regional Contact**

Americas

https://components.omron.com/us

Asia-Pacific

https://components.omron.com/ap

Korea

https://components.omron.com/kr

Europe

https://components.omron.com/eu

China

https://components.omron.com.cn

Japan

https://components.omron.com/jp